

**Lenz · El remapeador de teclados para el AFI · Versión 1.6**  
**Teclado español**  
**Scott Sadowsky · <http://sadowsky.cl>**

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[illegible]

	CTRL	WIN
ALT	CTRL + ALT	
ALT + MAYÚS	CTRL + MAYÚS	

WIN + MAYÚS	+ a b g d e s =	$\alpha \beta \gamma \delta \epsilon \sigma$
WIN	+ 6 7 8 9 0 =	$\lambda \vee 1 \downarrow \sim$
WIN	+ $\uparrow \downarrow$ =	$\nearrow \searrow$

The diagram shows a 3x3 grid world environment. The robot is represented by a small black square with a white arrow pointing right, located in the bottom-left cell (row 3, column 1). The goal is represented by a small black square with a white 'G', located in the top-right cell (row 1, column 3). Obstacles are represented by small black squares with white 'X's, located in the middle-right cell (row 2, column 3) and the bottom-middle cell (row 3, column 2). The cells are colored: black for the robot, light blue for the goal, and light green for obstacles. The other cells are white.